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ASSESSING RUTTING POTENTIAL OF STONE MASTIC ASPHALT USING WHEEL TRACKER AND DYNAMIC MODULUS TESTING

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Abstract. Rutting potential of stone mastic asphalt with varying aggregate gradations was assessed in the past mainly by uniaxial compression testing which is not the only test to predict its true performance in the field. Dynamic testing and accelerated wheel tracking test are considered the most suitable laboratory test procedures. Four stone mastic asphalt mixtures were prepared in this study using PG 58-22 binder, Viatop plus CT-40 fiber and four aggregate gradations with nominal maximum sizes of 9.5 mm, 12 mm, 19 mm and 25.4 mm. To access the effects of aggregate gradations, single type of bitumen, filler and fiber was used. Mixtures were tested and evaluated under both type of testing procedures at different temperature levels. A regression model was developed using wheel tracker test data to ascertain significant parameters that are directly influencing the rut depth. The statistics of the model shows an excellent degree of determinacy of 0.92 and a relative accuracy of 0.29. Sigmoidal functions using Witczak equations were determined from dynamic modulus master curves for characterization of mixes and compared with previous studies. Correlation between the wheel tracking factor and a dynamic modulus factor was also established at three frequency levels. The study reveals that a reasonable relationship exists between the wheel tracking factor and dynamic modulus factor for stone mastic asphalt mixtures.

Keywords: pavement, stone mastic asphalt, rut potential, aggregate, regression model, wheel tracking test.

1. Introduction

Stone mastic asphalt (SMA) generally consists of gap graded aggregate gradation bonded by mastic, which is combination of mineral filler, bitumen and a fiber (Brown *et al.* 1997). SMA contains higher binder content than a dense graded mix. Addition of filler and fiber in a SMA mixture mainly reduces the binder drain. This structure improves the strength and the performance of SMA. High percentage of binder content is important to ensure the durability and laying characteristics of SMA than conventional dense graded mixtures (Greer 2006; Tapkin, Ozcan 2012). Addition of fiber enhances the holding capacity of binder within the aggregate skeleton, otherwise fat spots on the pavement surfaces appear after construction. Also, aggregate type has influential effect on asphalt mixture performance (Haritonovs *et al.* 2013).

Several studies in the past mainly focused on the influence of different parameters on the SMA performance (Hafeez *et al.* 2014; Muniandy, Huat 2005). According to Brown *et al.* (1997), mastic is a mixture of bitumen, filler, sand and stabilizing additives. The stabilizing agents may be fibers (more effective in drain down) or modifiers (more resistant to rutting of SMA in the laboratory wheel tracking test). Filler is an important part of SMA to ensure proper stone-on-stone contact. The angular nature of filler effects on the stiffness of mortar (Brown et al. 1997). Similarly, aggregate in SMA should be strong enough to resist fractures and abrasion (Harris, Stiuart 1995). Xie and Watson (2004) reported variation of air voids in SMA and its influence on performance. Different methodologies have so far been used with different techniques and testing methods especially dynamic creep testing, wheel tracking test, dynamic modulus test, imaging technique, and voids in coarse aggregates (VCA) to ascertain SMA mixtures rut potential (Apeagyei 2011; Goh et al. 2011; Hafeez et al. 2009; Masad 2004; Pouget et al. 2014; Retherford, McDonald 2013; Seo et al. 2007; Sivilevičius 2011; Su et al. 2008; Watson 2003). Several studies in the past revealed that SMA mixtures perform better in rut resistance than superpave asphalt mixtures (Prowell et al. 2002; Schwartz et al. 2003; Watson et al. 2004).

Current study is focused on ascertaining the rut potential of SMA using wheel tracking test and dynamic modulus test and determining relationship between the findings of both the testing methodologies. Aggregate gradation was the major variable to be used.

2. Experimental program

2.1. SMA mixtures

Four aggregate gradations were selected to investigate the influence of size on rutting potential as reported in Table 1. For ease of readers, aggregate gradations have been presented with their Nominal Maximum Aggregate Sizes (NMAS). Three gradations, 25.4 mm, 19 mm and 12 mm NMAS were taken from AASHTO MP-8:2003 Standard Specification for Designing Stone Mastic Asphalt while fourth gradation with 9.5 mm NMAS was taken from Australian Asphalt Pavement Association (Hafeez et al. 2014). Aggregates were obtained from a local source of Margalla Crush Quarry, which is one of the best lime stone aggregate sources in Pakistan and meeting max demand of highways construction. The mechanical properties of aggregates were determined in accordance with American Association of State Highway and Transportation Officials, Washington D.C. specifications that included sizing and grading, particle shape (an average flakiness index of 7%), absorption (0.58%), sand equivalent (85%), toughness



Fig. 1. Aggregate gradations with NMAS

Table 1. Typical grading and bitumen content for SMA mixtures

Description of	SMA mixtures with NMAS			
properties	25.4 mm	19 mm	12 mm	9.5 mm
Optimum bitumen content (by mass of total mix), %	6.2	6.4	6.7	7.1
Bitumen type	PG58-22			
Air Voids (V_a), %	3.87	4.01	4.18	4.35
Voids in Mineral Aggregate (<i>VMA</i>), %	16.2	16.7	16.8	17
Fiber, %	Viatop cellulose fiber (0.3%)			

(19%), and soundness (2.32%). Fig. 1 shows typical percentages of aggregate gradation used in the mixtures.

Superpave method of mixture design was adopted for optimum bitumen content and air voids. Superpave gyratory compactor was found to produce less aggregate breakage than Marshall Compactor (Gao *et al.* 2014). Binder was selected from the single source, which is a major source of bitumen in Pakistan. The basic purpose of selecting the single type and source of binder was to minimize its variability effects on rutting potential of SMA. Bitumen content designed for mixtures was ranging from 6% to 7% at 0.3% of fiber content as reported in Table 1. Mixtures were prepared at design air voids ranging from 3.87% to 4.35%. Min voids in mineral aggregate were obtained in the range 16% to 17%.

Mastic for SMA's was prepared with PG 58-22 binder, filler (limestone dust) and Viatop cellulose fiber from J. Rettenmaier and Sohne (Hafeez et al. 2014) Germany. Viatop plus CT-40 fiber in the form of pellets was selected to prevent drain down of bitumen. It has significant elastomeric effects that contribute in the rut resistance of SMA mixtures. The purpose was to increase the stiffness in the form of rut resistance and to enhance the binder storage ability of SMA. The origin of Viatop fiber is ARBOCELL ZZ 8/1, which is mainly an adhesion promoter in the SMA and its dosage was 0.3% by weight of bitumen. The other constituent of Viatop was Fischer-Tropsch-Wax. Asphalt binder of PG 58-22 was recommended by JRS, Germany to combine with Viatop plus CT 40 fiber for SMA preparation. It offers the best characteristics to disperse a fiber pellet properly in the pug mill including good economical aspects.

2.2. Wheel tracking test

Slab specimens of $40.3 \times 40.3 \times 7.5$ cm size were prepared using a roller compactor and conducted a wheel tracking test at 720 Newton load. The lift thickness of slab specimens was taken as 7.5 cm to cover the max size of 25.4 mm. The compaction pressure and number of roller compactor passes were selected to control air voids of SMA. Specimens in three replicates were tested under wheel tracking at 25 °C, 40 °C and 60 °C. This temperature range was selected on the basis of field conditions. The moving table in a wheel tracking test as shown in Fig. 2 reciprocates at a frequency of 53 passes per minute. The formation of rut was measured using linear variable differential transducers in accordance with *BS EN12697-22:2003 Bituminous Mixtures. Test Methods for Hot Mix Asphalt. Wheel Tracking.*

Wheel tracking machine applied 10 000 cycles of load on SMA mixtures and recorded the rut depth at each cycle. Rut depth data at each 400 cycle was extracted for



Fig. 2. Wheel tracking machine (after Cooper 2006)

plotting the graphs. The main purpose of selecting 25 points in 10 000 cycles, each at every 400 cycle was to make a good presentation of mixture's rut development. Influence of load cycles on rut depth at 25 °C, 40 °C and 60 °C have been shown in Fig. 3. It may be noted from Fig. 3 that that rut depth formation depends on number of load repetitions at a specific temperature. Plots show that with an increase in aggregate gradation size of SMA, rutting depth decreases. The summary of rut formation of SMA mixtures at 10 000 load cycles has presented in Table 2. At 60 °C, SMA mixture with 25.4 mm NMAS showed minimum value of rut depth and SMA with 9.5 mm NMAS yield highest value.

Regression analysis was performed on wheel tracking data of SMA mixtures against load cycles and correlations between rut depth and load cycles were developed on Log space as typically shown in Fig. 4. The intercept coefficient *a* and the slope coefficient *b* was determined at different temperatures from following typical linear fit line equations:

$$y = b\ln(x) + a,\tag{1}$$

where a and b – the intercept and slope coefficient of the best fit straight line.

The rut rate in the form of slope coefficient is an important parameter that defines rut potential of asphalt mixtures. Fig. 5 shows the influence of max size of aggregate gradation on slope coefficient in a bar chart form. It may be noted that slope coefficient decreases with an increase in the max size of aggregate gradation and has max value at 60 $^{\circ}$ C.

It may be noted from Fig. 5 that resistance to rut of asphalt mixture increases with an increase in the nominal max size of aggregate gradation. Slope coefficient is an indicator of asphalt mixture's resistance to rut. With an increase in temperature the slope coefficient increases.

2.3. Dynamic modulus testing

Specimens (150 mm diameter by 180 mm thick) were prepared for four SMA mixtures, which were cored and cut to final size of 100 mm diameter by 150 mm thickness. Average air voids of cored specimens were in the range of 3.32% to 4.05%. Dynamic modulus test was performed according to AASHTO TP-62:2004 Standard Method of Test for Determining Dynamic Modulus of Hot-Mix Asphalt Concrete Mixtures at 25 °C, 40 °C and 60 °C. A sinusoidal compressive stress wave was applied to test specimens at loading frequencies of 25 Hz, 10 Hz, 5 Hz, 1 Hz, 0.5 Hz and 0.1 Hz. A stress level of 500 kPa, 200 kPa and 50 kPa was selected at 25 °C, 40 °C and 60 °C, respectively. The objective of applying stress control mode was to get lower numbers of cycles to failure as compared to controlled strain test.

Results of dynamic modulus test at specified stress level at each temperature have only been reported in this study for comparison. Dynamic modulus and phase angles were recorded at each frequency and temperature level. It may be noted from Fig. 6 that temperature and frequency levels have significant influence on the dynamic modulus of SMA mixtures. In comparison, mixture with 25.4 mm max aggregate size gradation produced higher value of



Fig. 3. Rut depth formation of SMA at: a – 25 °C; b – 40 °C; c – 60 °C

Table 2. Rut depth in SMA mixtures tested under the wheel tracking machine

	Rut depth of SMA mixtures			
NMAS size, mm	at 25 °C	at 40 °C	at 60 °C	
		mm		
25.4	2.15	4.68	6.61	
19	2.51	6.96	9.04	
12	2.72	9.98	12.18	
9.5	3.14	12.8	15.15	

dynamic modulus. Typical master curves at reference temperature of 25 °C were constructed to complete the characterization of SMA mixtures. Individual stiffness curves before applying a shift factor has been shown in Fig. 6. An arrow mark shows a direction of shift of one temperature data to a reference temperature data. Fig. 7 shows a developed master curve between Log of Reduced Time (T_r) and Log E^* . T_r is difference of time of loading (reciprocal of frequency) and logarithm of shift factor.

Master curve development using a dynamic modulus test data is considered as a critical input in flexible pavement design. Master curve helps in predicting the influence of different parameters on asphalt mixtures performance.



Fig. 4. Typical plot for intercept and slope coefficient copmutation



Fig. 5. Summary of slope coefficient for SMA mixtures



Nonlinear regression technique using a software packages was performed on the measured dynamic modulus test data. The shift factors (a_T) at each temperature were determined and plotted against temperature as shown in Fig. 8. Shift factor (a_T) determines the amount of shift that has been made to superimpose the frequency-stiffness data at any temperature to a specific temperature. It is a ratio of time that is required to give a specified response at a certain temperature and the time required to give an identical response at the reference temperature. It may be noted that the temperature susceptibility of SMA mixtures depends on aggregate gradation. With an increase in the size of aggregate gradation the SMA mixture susceptibility to rut reduces.

The dynamic master curves have been presented by the sigmoidal functions as described by *Mechanistic-Empirical Pavement Design Guide 2008* by American Association of State Highway and Transportation Officials in the following equation:

$$Log\left|E^*\right| = \delta + \frac{\alpha}{1 + e^{\beta + \gamma(\log T_r)}}.$$
(2)

The fitting parameters δ and α depend on aggregate gradation, binder content and air void and also represents the max and min values of the modulus. The sum $\delta+\alpha$ also represents the max value of applied stress that damages the



Fig. 7. Developed dynamic modulus master curves for SMA mixtures after shifting



Fig. 8. Comparison of horizontal shift factors for SMA mixtures

specimen. The shape parameters β and γ depend on characteristics of asphalt binder. A brief summary of above function has presented in Table 3.

Sigmoidal functions help to characterize the master curves in terms of shape and locations. Different values of these functions against different set of input data have been reported by researcher in the past. For comparison few results have been reported in Table 4.

Tables 3 and 4 show that values of sigmoidal function depends upon mix properties and testing features that mainly involve type of testing, material types and test conditions. Sigmoidal functions are sensitive to asphalt binder and mixtures properties (Hafeez *et al.* 2013; Zhao *et al.* 2013).

3. Results and discussions

3.1. Rut Prediction Model

A regression model was developed using the wheel tracking test data that determines the influence the aggregate gradation in terms of nominal max size D on the resultant rut depth h. Other parameters like air voids, bitumen content and the voids in mineral aggregate vary in a narrow range in the mixtures and have no significant effect on the model. The MEPDG power model was followed for determination relationships between the predicted and the measured permanent to recoverable ratio under each test condition. Microsoft Excel Solver tool was applied for least square regression analysis to measure rut depth h. The least values of nonlinear regression coefficients (a_1, a_2, a_3) a_3, a_4) were determined to define relationship between the predicted and measured depth at any number of load cycle "N". The following model on the basis of the goodness-offit parameters was established:

$$h = a_1 \frac{T^{a_2} N^{a_3}}{D^{a_4}}.$$
 (3)

The above equation may be presented as

$$h = 0.0008 \frac{T^{1.22} N^{0.67}}{D^{0.60}}.$$
 (4)

Statistics of the model: $R^2 = 0.92$ (Coefficient of Determination); $S_y = 3.05$ (Standard Deviation); $\frac{S_e}{S_y} = 0.29$ (Relative Accuracy); observation points = 3564.

The power coefficient of load cycles and aggregate size in the above model are close that indicates the relative importance of both the variables. The temperature coefficient has almost double value than the load cycle and size of aggregate that means it has relatively twice the impact over the rut potential of SMA. Taking the logarithm and transforming into a linear form, the above model may be presented as

$$\log(h) = \log 0.0008 + 1.22 \log T + 0.67 \log N - 0.6 \log D.$$
 (5)

Predicted and measured rut depths data was plotted on a single space to ascertain the relative accuracy of the model. Data within the secondary zone of permanent deformation are shown in Fig. 9 that depicts minimum bias in the model. Horizontal axis represents the rut depth data of different SMA mixtures at different temperature levels obtained from wheel tracking machine. Vertical axis represents the data of SMA mixtures at different temperature levels obtained from the above regression model for 10 000 load cycles values. Each curve on measured-prediction model data scale represents a rut data of a mixture obtained at any of the temperatures (25 °C, 40 °C or 60 °C). Straight line at each test condition followed a 45° line trend which shows an excellent degree of agreement between the measured and the predicted data.

Statistics of the model enhances author's confidence towards the utilization of regression model in further

Table 3. Parameters for dynamic modulus master curve

Davamatara	SMA mixtures designation with NMAS			
Parameters -	25.4 mm	19 mm	12 mm	9.5 mm
δ	1.43	1.50	1.54	3.85
α	2.18	2.21	2.35	2.95
β	-1.60	-1.85	-2.25	-3.39
γ	0.88	0.82	0.71	0.56

Table 4. Sigmoidal functions reported in other studies

References of previous studies	Sigmoidal functions		
Rowe <i>et al.</i> (2009)	Witczak parameters computed with RHEA Software:		
	For mix at 3.8% air voids $\delta = -0.954$, $\alpha = 4.613$,		
	$\beta = -1.64, \gamma = -0.428.$		
	Richard parameters for dynamic modulus master curve:		
	For mix at 3.8% air voids $\delta = 0.301$, $\alpha = 4.094$,		
	$\beta = -1.513, \gamma = -0.395.$		
Kim and	For Mastic asphalt tested under uniaxial compression test:		
Partl (2009)	δ = 1.350, $α = 1.860$, $β = -2.820$, $γ = 0.680$.		
	For in place hot mix asphalt cores taken from		
Flintsch	18 sites		
et al. (2006)	Average values δ = 4.2837, α = 2.1672,		
	$\beta = -0.6373, \gamma = 0.5853.$		



Fig. 9. Measured versus predicted rut depth

analysis and comparison with the dynamic modulus test data in the laboratory. The model was further analyzed for percentage error to measure the range of percentage difference between the measured and observed data. Frequencies of observations were recorded against each percentage differences and the frequency of observation was plotted to measure the significance of model. Results of histogram as shown in Fig. 10 revealed that 90% of percentage differences are within $\pm 1\%$ with a median value of -0.085.

It may be noted from Fig. 10 that variation in the values within the data range is low and the median value is acceptable. The statistical analysis of the model shows that the input parameters are in close agreement and has influential effects on the rut resistance of asphalt mixtures.

3.2. Wheel tracking factor and $\frac{|E^*|}{\sin(\delta)}$

Among the six frequency levels (25 Hz, 10 Hz, 5 Hz, 1 Hz, 0.5 Hz and 0.1 Hz) used in dynamic modulus test, results of



Fig. 10. Percentage differences between the observed and the predicted rut depth

Table 5. Comparison of rut depth with $\frac{|E^*|}{\sin(\delta)}$ values at different frequencies

Rut depth measured from wheel tracking	-	$\frac{ E^* }{\sin(\delta)}$ values at	
in descending order	1 Hz	0.5 Hz	0.1 Hz
2.79	12 211.81	11 967.57	11 608.50
3.32	9315.83	9036.36	8674.90
4.38	6119.57	5844.19	5493.54
4.95	5958.30	5600.80	5096.73
5.03	4732.76	4354.14	3744.56
5.89	4562.54	4060.66	3248.53
7.30	1994.89	1675.71	1240.02
7.76	3339.20	2604.58	1692.97
8.69	1257.76	893.01	491.16
8.93	2621.78	1651.72	726.76
11.45	862.08	474.14	156.47
13.17	725.41	319.18	73.41

lower frequency levels of 1 Hz, 0.5 Hz and 0.1 Hz have been reported in this study. Although these frequency levels are not true representative of slow moving trucks in the field, but still they are considered critical in well performing the asphalt mixtures under cyclic loading. Low frequencies are normally selected for the design of parking areas. Also, the wheel tracking test traveled at a speed of 1.44 km/h (Bahia, Anderson 1995), which is a representative of computing the same effect. An effort was made to compare dynamic modulus test at middle stress levels (200 kPa) as reported in Table 3 with the wheel tracking at lower frequencies. The objective is only to simplify and signify the influence of high temperature and low frequency levels on correlation between the results of both the tests. A parameter $|F^*|$

 $\frac{|E^*|}{\sin(\delta)}$ for SMA mixtures was computed and presented at

low frequency levels. Wheel tracking factor, which was the computed rut depth from the regression model, was then plotted against the dynamic modulus test parameter $\frac{|E*|}{\sin(\delta)}$. Data presented in Table 5 between the wheel $\sin(\delta)$ tracking factor and $\frac{|E*|}{\sin(\delta)}$ at each frequency level are shown in Fig. 11.

Strong relationship exists between the wheel tracking factor and $|E^*|/\sin(\delta)$ as shown in the following equations:

at frequency of 1 Hz, $y = 21641e^{-0.1308x}$, $R^2 = 0.93$, (6)

at frequency of 0.5 Hz, $y = 29029e^{-0.1682x}$, $R^2 = 0.97$, (7)

at frequency of 0.1 Hz, $y = 50113e^{-0.2361x}$, $R^2 = 0.98$. (8)

Whereas *x* and *y* in above equations presents the wheel tracking factor and $\frac{|E^*|}{\sin(\delta)}$, respectively. It may be noted from Eqs (6)–(8) that both the constants increase with a decrease in frequency level, which clearly indicates the influence of frequency level on the rut prediction factors. Higher rut depths were observed at low frequency level because of asphalt being a visco-elastic (time dependent) material.



4. Conclusions

Based on testing and analysis of results, the following conclusions have been drawn.

1. Maximum size of aggregate and temperature has significant influence on the rut potential of stone mastic asphalt mixtures. By increasing maximum size of aggregate gradation from 9.5 mm to 25.4 mm, around 60% rut value of mixtures reduced at temperature of 60 $^{\circ}$ C.

2. The proposed model from the wheel tracking test data depicts that the rut depth as a function of number of load cycles, temperature and maximum size of the aggregate gradation at a relative accuracy of 0.29 and degree of determination of 0.92.

3. At lower frequency levels relationship between the wheel tracking factor and $\frac{|E^*|}{\sin(\delta)}$ becomes stronger as R^2 enhances from 0.93 to 0.98. Also, the slope and intercept coefficients of these relationships were observed to be increased by almost 100%.

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